AUTO-FOCUS

The ASI auto-focus system uses an electronic circuit to detect the high spatial frequency information present in a video signal coming from an analog camera, and converts it to a *focus value* for each frame – the better the focus, the larger the *focus value*. Depending on the sample and the type and power of the objective, the conditions to achieve the best *focus value* may change. To compensate, the system incorporates an auto-calibration routine that automatically sets various internal parameters to get a good *focus value*. The system also allows you to highlight any subset of the video field and focus on an object in it.

Video IN from Camera

Video OUT to Monitor

(a)

Sampled / Highlighted Area

Standard Video

(b)

Fig 1: (a) Relevant Auto-focus Connections (b) Screenshot of Video Monitor signal from the Auto-Focus controller showing Sampled/Highlighted Area

When the controller is given an auto-focus command, it moves from a starting position to a stop position, constantly checking the focus signal. The focus signal goes through a filtering process to remove unwanted false focuses caused by noise and other disturbances. In "*Normal*" mode, the controller takes the filtered signal and watches for the maximum value. When a new maximum value is detected, the controller keeps track of the position where it was found. When
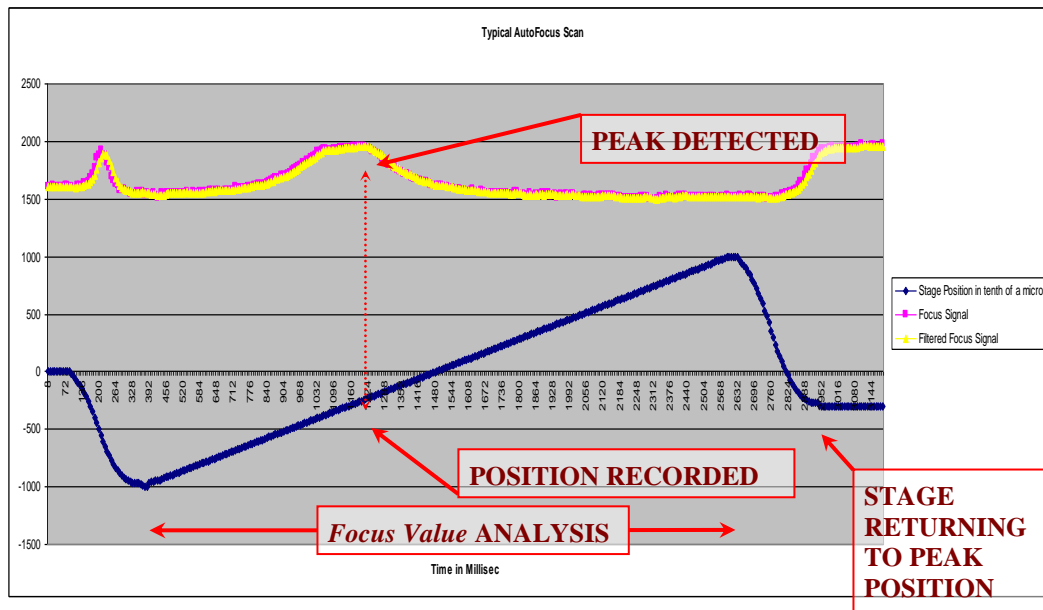

Fig 2: A "*Normal*" auto-focus scan showing a stage's focus-axis position in tenths of microns, and the focus signal and filtered focus signal *(focus-value)* extracted from input video signal.

the end of the scan is reached, the controller goes back to the position that had the highest value.

There is also a "*Hill Detect*" mode available. In this mode, the auto-focus controller watches for the *focus value* to increase in value and then start to decrease, thus detecting a hill. At this point, the auto-focus controller stops the scan and goes back to the position that had the highest *focus value* found on the hill. This is somewhat subject to false focusing and should be used only on high contrast single-layer samples with sharp edges.

AUTO-FOCUS ALGORITHM

An actual auto-focus is initiated with the **AFOCUS** (or **AF**) command without any arguments; however, the system should first be set up. Auto-focus is configured by the **AFOCUS** (or **AF**) command with arguments specifying the *speed* at which to scan, the *travel distance* to be scanned, and the scan type. All or none of these arguments can be entered when issuing the command, as the auto-focus controller remembers the last parameters given and will only change the parameters specified in the new **AF** auto-focus command. This allows the user to repeat the last command without having to resend all the arguments.

The **AFOCUS** (or **AF**) arguments affect the auto-focus configuration in the following ways:

AF X= [% of *speed*] **Y=** [*travel distance* in mm] **Z=** [*Hill Detect enable*] **F=** [*Hill Offset*]

% of *speed*:   *Speed* can be set with the **X** parameter in a range from **1** to **100**. If the **X** parameter in the command is not specified or the value of **X=0** is entered, the last value given will be used. (The default value of **10** will be used if nothing has been entered.)

The hardware auto-focus circuit generates a new *focus value* for every video frame (every 16 milliseconds for an NTSC/RS170 camera). This acquisition rate, along with the scan *speed*, determines the axial resolution obtainable with the auto-focus system. For instance, if the scan rate is 0.1 mm/sec, then the distance between *focus values* will be

$$0.1 \text{ mm/second} \times 0.016 \text{ seconds/frame} = 1.6 \text{ μm/frame}$$

This *speed* would give roughly a 1.6 μm focus resolution. Typically, ASI's focus drives have a maximum auto-focus speed of about 0.6 mm/second, so this resolution would be obtained with the scan *speed* set to approximately **16** *(% of maximum)*. For a high power objective lens, you may want to use a scan *speed* of perhaps **5** *(% of maximum)*, to yield a resolution of about

$$5\% \times 0.6 \text{ mm/second} \times 0.016 \text{ seconds /frame} = 0.48 \text{ μm/frame}$$

The trade-off when scanning at a slower *speed* for better resolution is the extra time it takes to complete the scan. For the fastest operation, pick the maximum *speed* that gives you the resolution you require and choose a small *travel distance*.

Travel Distance: Entered in millimeters, this is the distance the focus drive is allowed to move while looking for the best *focus value*, with one exception: when correctly zeroed before executing the **AFOCUS** (or **AF**) command, the drive will not travel more negative than

-200 μm from its zero position. This optional parameter in the **AFLIM** (or **AL**) command is designed to prevent damage to the sample or to the optics.

Type of Search: Two different types of search modes are available: *Normal* and *Hill Detect*.
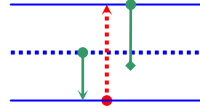
> ***Normal:*** Enabled when **AF Z=0**. In this mode, the controller moves down 1/2 the *travel distance*, scans up the full *travel distance*, and then returns to the position that had the peak *focus value*. This is the Default mode.

> ***Hill Detection:*** Enabled when **AF Z=1**. In this mode, the controller moves down 1/2 the *travel distance*, then starts to scan up until the *focus value* rises from its lowest value to a peak then begins to decrease back to a lower value again. When this hill is detected, the controller will return to the position that had that maximum *focus value* at the top of the hill. This search is generally used to find the first focus point. Note that if no hill is found, the controller will return to the highest *focus value* detected after reaching the end of the full *travel distance*.

> The **Hill Offset** value is the percentage that the *focus value* must decrease from its recent maximum before the scan is satisfied that a hill has been detected.
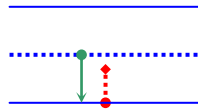
AUTO-FOCUS CONFIGURATION

To ensure safe and proper operation during auto-focus moves, perform the following procedure:

1. Focus the sample manually and then press the ZERO button on the controller. When correctly configured, the controller will never auto-focus to a position greater than 200 μm in the negative direction from the **0000** positioned. (This safety feature may be disabled by the **AFLIM** (or **AL**) command – see page 12.) By zeroing the controller at a typical focus location, you should have a reasonable range for the auto-focus to operate yet still protect an objective from crashing into the sample (Fig 3). You can also use the **HERE Z=0** command to zero the Z-axis position with software, if Z is the focus axis.
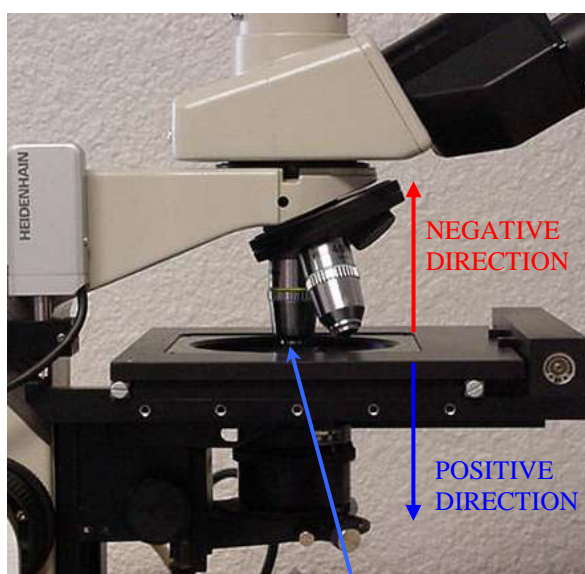

Fig 3: Set objective farther than 200 microns from the sample, then set the focus drive's position to ZERO.

2. Insure that **DIP Switch 2** on the back of your controller to UP position (Fig. 4). Your LCD will now display the *focus value* marked as **F:####** on its bottom line. This number will always be between **0000** and **2047**. **0000** indicates that little or no video signal is getting to the auto-focus card; check your connections. If the *focus value* reads **2047**, then the system is saturated with too much signal; try adjusting the Video Gain, Brightness, and Contrast controls on your camera if available. If this does not help, then go to step 4.
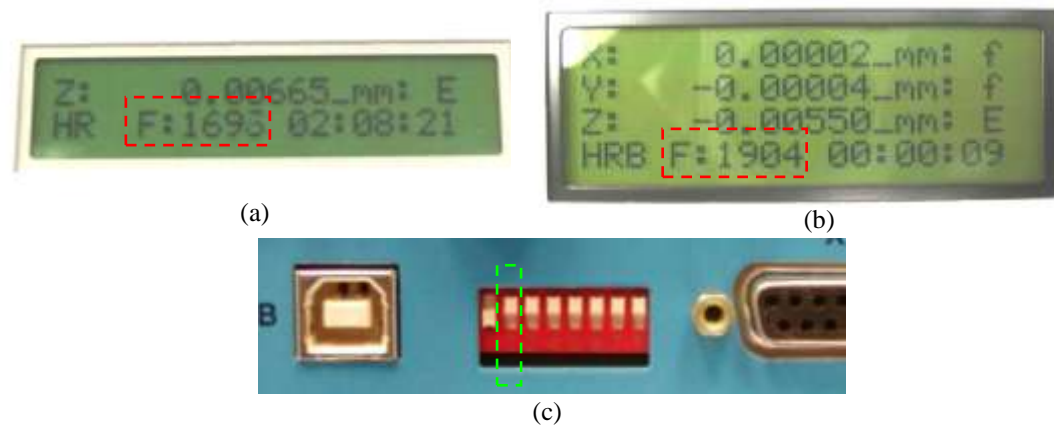
Fig 4: Shows the focus value as **F:1696** on a two-line LCD display (a) and as **F:1904** on a three-line LCD display (b). **Dip Switch 2** on the back of a controller in the UP position (c).

3. By focusing through your sample, you can watch the *focus value* change on the LCD screen. When the sample is held steady, the *focus value* on the LCD should remain steady; ideally, only the last digit should fluctuate by one or two counts. This is due to slight noise in the system and is tolerable. If the fluctuations are bigger, check the connections for any problems.

4. **AFCALIB** (or **AFC**) **X=** defines the *contrast* parameter for the auto-focus system. During an auto-focus run, if the controller finds the maximum and minimum *focus value* less than the *contrast*, it declares the run a failure and returns to the starting position. The **AFC X** value should always be more then the *focus value* fluctuation that you saw in step 3. Default value is **10**.

5. Next, using the **AFOCUS** (or **AF**) command, pick the auto-focus *speed* and *travel distance* suitable for your sample type, objective, and optics. A "*Normal*" focus on the slowest *speed* is often the best option – we recommend a *speed* less than **20** (% of the maximum speed of your focus controller). If you anticipate always being near the focus position, you can set a 10 to 50 micron range and swiftly get to the best focus in that range. The command for a 50 micron travel range would be:

    AF X=5 Y=0.05   where **AF X=** [% of *speed*] **Y=** [*travel distance* in millimeters]

6. Next, issue an **AFCALIB** (or **AFC**) command without parameters. This will begin the Auto-Calibration routine. The **AFC** routine will carry out a series of focus scans to automatically find and set various internal parameters to get a large *focus value* and enough *contrast* to avoid any false positives. It uses the *speed* and *travel distance* currently set by the **AF** command. It does not use the *Hill Detect enable* or *Hill Offset* settings – the Auto-Calibration routine will perform its scans in "*Normal*" mode over the full *travel distance*.

7. Finally, perform a regular auto-focus run using the **AFOCUS** (or **AF**) command to see if the new settings work. If the results are satisfactory, you can save these settings with an **SS Z** command, otherwise they will revert to their previous values upon reset or power down.

8.   If the focusing is inconsistent, try the Manual Calibration steps found in the following section. For additional help contact Support@ASIimaging.com.

MANUAL CALIBRATION

The `AFCALIB` (or `AFC`) Auto-Calibration routine tunes the system moderately so that the system works for most samples and objectives. Try the following steps for better results:

1. Manually focus the sample and insure that **DIP Switch 2** on the back of your controller is in the UP position. It will now display the *focus value* marked as `F:####` on the bottom line of your LCD. This number will always be between `0000` and `2047`.

2. Next, set `AFADJ X=0 Y=0 Z=0`

    The `Y` value sets an internal digital potentiometer that controls the video signal amplitude. Its range is from `0` to `100`. A value of `0` completely attenuates the video signal, while `100` permits 100% of the video signal to be used.

    With `Y` set at `0`, there is no video signal in the system, therefore the *focus value* should also be `0000`. However, due to various reasons like noise, initial offsets, etc., the *focus value* as displayed on the LCD may larger. The `X` value of the `AFADJ` command sets a "zero-adjust potentiometer". Starting from `0`, slowly increase the `X` value in steps of `5` to `10` until the *focus value* reads as close as possible to `0000`. When you find the right value, you will have set up the auto-focus system such that, with zero video signal, the *focus value* is also almost zero. At this point, the *focus value* will be totally dependent on the video input and not on any internal noise or offsets. The value of `X` you find depends solely on the controller electronics and should not vary with your samples, your optics, or your camera setup.

    If this step is not performed, over time, the internal noises and offsets will accumulate, and the *focus value* will ramp up and saturate.

    The `Z` value sets the gain of an Analog-to-Digital converter (ADC) which is connected to an internal integrator that converts spatial frequencies into the *focus value*. A value of `0` indicates a gain of 1x – for now leave it set at `0`.

3. Now, to tune other parameters, insure that your camera is connected and feeding video into the auto-focus card. Allow some video signal into the system by increasing the `Y` value of the `AFADJ` command to approximately `90`.

4. The `AFLIM` (or `AL`) command's `X` and `Y` values adjust the highlighted or sampled video area as seen on the Video OUT port when viewed on a monitor. Only the highlighted video frame area is used for auto-focusing. The `X` and `Y` range is from `0` to `100`. A value of `0` highlights 0% of the respective `X` or `Y` axis, while `100` highlights almost 100% of the respective axis. Select a value such that the sample object you are interested in falls in the highlighted area and any unwanted artifacts are excluded. You can set the `X` and `Y` values generously: the larger the sampled area, the better the *focus value*.

    By default, the highlighted area is centered in the video frame. If you want to offset this area, carefully adjust the two potentiometers mounted on the auto-focus circuit board.

5. Next, set the **AFADJ Z** value, i.e. the ADC gain. Setting **AFADJ Z=1** will double the *focus value* as seen on the LCD screen, **z=2** will quadruple, and **z=3** will octuple. When you feel you have found a right value, try moving your sample in and out of focus to check that the *focus value* does not rise to **2047**. When the *focus value* reads **2047**, the system is saturated – try turning the gain down to the next lower value.

AFADJ	*Focus Value Multiplier*
Z=0	1x
Z=1	2x
Z=2	4x
Z=3	8x

6. Now re-adjust **AFADJ Y** value to fine-tune the video strength. Increase **Y** value until it just reaches the **2047** ceiling, and then decrease it a little. When you feel you found a right value, try moving your sample in and out of focus and check that the *focus value* is not saturating at the **2047**.

7. The auto-focus system works well when the difference between the in-focus *focus value* and the out-of-focus *focus value* is large. The *contrast* value, as set with the **AFCALIB** (or **AFC**) **X** command, should be larger than the *focus value* fluctuations seen when the sample is held steady, but smaller than the difference between the in-focus and out-of-focus *focus values*. The correct *contrast* value helps avoid false focusing. If the controller finds the difference between the maximum and minimum *focus value*s to be less than the *contrast*, it declares the run a failure and returns to the starting position.

8. If the system consistently settles at a spot that is a bit off the focus or the image is not sharp enough, try adjusting the **AFCALIB** (or **AFC**) **Y** or *frame offset* value. Since the focus controller's speed and video frame rate are not synchronized, the auto-focus controller uses the *frame offset* value to calculate the correction needed to move the sample to the correct focus position. For NTSC cameras used with ASI's motorized focus controllers or piezo-Z stages, the *frame offset* is commonly between **3.5** and **4**.

9. Another parameter that can help with better scanning is the scan *speed* as set with the **AFOCUS** (or **AF**) command's **X** parameter which ranges from 1% to 100% of maximum of the focus drive's speed. A slower *speed* takes a longer time but ensures better focus results. Typically, ASI's focus drives have a maximum auto-focus speed of about 0.6 mm/second.

TROUBLESHOOTING AND OPTIMIZATION

Focus value on the LCD ramps up and saturates when the sample is motionless and the focus controller is quiescent.

This problem occurs when the *Zero Potentiometer* (set by **X** argument of **AFADJ**) is incorrectly set. This can be corrected by running the Auto-Calibration routine (**AFCALIB** or **AFC**) or by performing Step 2 of Manual Calibration (page 7).

Hill Detect does not work well.

Two parameters that greatly influence Hill Detect performance are *Hill Offset* (set by the **F** argument of **AFOCUS** or **AF**) and *Contrast* (set by **X** argument of **AFCALIB** or **AFC**).

If the Hill Detect continues to scan the sample for considerable time after passing the best focus, it could be caused by large **AF** *Hill Offset* percentage – try decreasing it.

If the Hill Detect returns a false focus, try increasing the **AFC**'s *contrast* value or try increasing the **AF**'s *Hill Offset*.

Stage returns to a position just off the best focus spot.

There are two things you can do to improve this: try rescanning with lower *speed* setting (set by the **X** argument of **AFOCUS** or **AF**) or try changing the *frame offset* (set by **Y** argument of **AFCALIB** or **AFC**).

To determine which option is best for you, try the following: manually focus through the sample and stop at the spot where you read the highest *focus value* (**F:####** value on bottom line of your LCD). Store this position by pressing the ZERO button or by issuing the **ZERO** or **Z** software command. Now run auto-focus with the **AFOCUS** (or **AF**) command or by pressing the @ button on the controller a couple of times. If the focus controller consistently returns around the same incorrect position, then changing the *frame offset* is a good solution. On the other hand, if it randomly returns to a position on the **+** or **−** side of **0.00000**, then reducing the *speed* is your best option.

Frame offset is a constant that depends on your camera's frame rate and your focus drive's speed. This setting compensates for time lags inherent in the video processing. The default value for an ASI motorized focus controller and an NTSC camera is **3.5**, however. If you were using a faster focus drive such as ASI's piezo-Z stage, your *frame offset* would be about **3.75**. If you are using a digital camera in progressive scan mode, your *frame offset* could be as high as **4**.

Unfocused spot has a higher focus value than a focused spot.

Here are a few things you can try when the *focus value* reads a higher value at a defocused spot than at a focused spot:

- Turn off any Automatic Gain Control (AGC) settings on your video system and use a Manual or Fixed Gain setting instead.
- The illumination might be insufficient; increase the lighting on your sample.

- Limiting the background might help; decrease the highlighted screen area with **AFLIM** (or **AL**) command.

AUTO-FOCUS High Level COMMANDS

See the MS-2000 Programming Section for a complete listing of all MS-2000 serial commands and details of the RS-232 interface: http://www.ASIimaging.com/pdfs/Operations_and_Programming_Manual.pdf

Command: AFADJ

Format:	**AFADJ** [**X=** *zero pot value*] [**Y=** *video amplitude value*] [**Z=** *value*]

Function: **X** & **Y** values range between **0** and **100**. **Y** determines amplitude of the video signal entering the system. Setting a **0** value attenuates a video signal completely, while a setting of **100** lets the full signal go through. Attenuating a video signal also reduces the noise in the signal. If the focus value on the LCD reads **2047**, then the system is saturated with too much signal, try reducing the **Y** value.

X is the zeroing potentiometer; the value of **X** should be set such that, when **Y** is **0**, the *focus value* is also **0000** (or as close as possible).

Z sets the gain of the final Analog to Digital Converter (ADC) in the auto-focus system. Range: **0** to **3**. By adjusting this setting, a *focus value* for a sparse sample can be magnified to get better focus. If an incorrect value of gain is used, the ADC saturates and the *focus value* reaches **2047**. Upon system restart, the setting returns to its default value of **0**. Perform an **SS Z** command to save the current gain setting in non-volatile memory.

AFADJ	GAIN
Z=0	1x
Z=1	2x
Z=2	4x
Z=3	8x

Response	**:A** or Error Reply (see below).
Examples:	**AFADJ X=15 Y=95** **:A<CR><LF>**
Command	**AFADJ**
Reply	**:N-3** (Error indicates missing arguments)

Assign	**AFADJ X=1000 Y=-12 Z=4**
Reply	**:N-4** (Error indicates arguments out of range)
Assign	**AFADJ X=20 Y=90**
Reply	**:N-5** (Error indicates operation failed, try entering one argument at a time)
Query	**AFADJ X? Y?**
Reply	**:A X=20 Y=95**

Command: AFCALIB

Format: **AFCALIB** [**X=** *contrast*] [**Y=** *frame offset*] [**F=** *switch axis*]

Shortcut: **AFC**

Function: The command without arguments will initiate series of auto-focus scans and selects various internal parameters for best focus value. Parameters changed by **AFCALIB** are the *Highlighted Area* (**AFLIM**), *Zero Adjust* (**AFADJ**), and *ADC Gain* (**AFADJ**). On some focus controllers, the **AFCALIB** routine can also be activated by holding down the "HOME" button for longer than 3 seconds. The **AFCALIB**'s auto-calibration scans use the same *speed* and *travel distance* value that were set by the **AFOCUS** (or **AF**) command. **NOTE:** Please use the **HALT** command or the **"\"** to cancel an auto calibration – any other method may stop the move but may corrupt your settings.

X= Sets the minimum *contrast* value. During an auto-focus run, if the controller finds the difference between the maximum and minimum *focus value* to be less than the *contrast* value, it declares the run a failure and returns to the starting position. Default value is **10**.

Y= *Frame Offset*, a floating-point constant that maps to a time interval. Changing this number alters the sharpness of focus. The default values are **3.5** for motor-driven focus drives, and **3.75** for piezo-driven focus drives. This setting compensates for time lags inherent to the video processing.

F= *Switch Axis*; if your focus controller can control two focus axes, e.g., a motorized drive and a piezo drive, then you may have the option to choose which axis to use for auto-focusing. Every axis that the focus controller controls is assigned a number starting from zero. Check with ASI to determine if this option is available for your system and to get the number for each axis.

Executing **AFC** alone will begin the Auto-Calibration routine. Using **AFC** with arguments will only set or read back those parameters.

Response   **:A** or Error Reply (see below).

If the **X**, **Y** and **F** arguments are omitted, then an **A** is returned after the calibration is complete.

<u>Examples:</u>	**AFC**
	:A\<CR>\<LF>
Assign	**AFC X=8 Y=3.75**
Reply	**:A**
Query	**AFC X?**
Reply	**:X=8 A**
Command	**AFC**
Reply	Returns an **:A** after operation is complete, an **:N-5** if the operation failed, or an **:N-50** if the focus drive's clutch is disengaged (if applicable).

Command: AFINFO   (version 8.7+)

Format:	**AFINFO**
Function:	This command returns all the values of variables and constants that control Autofocus. It also returns maximum focus value found during last autofocus run, original location and location after frame offset was applied.
<u>Examples:</u>	**AFINFO**

Best Focus:587

Position Preoffset: 0.0002 mm Afteroffset: -0.0003 mm

Speed : 1   [AF X]

Travel:0.025000 [AF Y]

Frame Offset:3.500000 [AFC Y]

Hill Offset:70 [AF F]

Contrast:10 [AFC X]

Window Size X:98 Y:98 [AL X Y]

Zero ADJ X:50 Y:90 [AFADJ X Y]

ADC Gain:0   [AFADJ Z]

\<LF>

Related commands are shown inside square brackets, which you can use to change parameters, where applicable

Sometimes because of limited storage space a lite version of the command may be available. It will only displays Best Focus, Positions preoffset and afteroffset.

Best Focus:587

Position Preoffset: 0.0002 mm Afteroffset: -0.0003 mm

Command: AFLIM

Format: **AFLIM** [**X=** *x-axis highlight*] [**Y=** *y-axis highlight*] [**Z=** *safety limit enable*]

Shortcut: **AL**

Function: The **X** and **Y** values set the length and breadth of the Sampled/Highlighted Video area. Range is **0** to **100**, with the value of **0** covering 0% of the video frame and **100** covering 90% of video frame.

The **Z** value enables or disables the 200 µm *safety limit* described in the AUTOFOCUS OPERATION section on page 4. Setting *safety limit enable* = **1** enables the safety limit; *safety limit enable* = **0** disables the safety feature. The default value is **1**. ***Caution: Disabling the* safety limit *could result in damage to your optics, your sample, or your focus drive.***

Response   **:A** or Error Reply (see below).

Examples: **AL X=80 Y=50 Z=1**
                 :A<CR><LF>

Command   **AL**

Reply   **:N-3** (Error indicates missing arguments)

Assign   **AL X=1000 Y=-12**

Reply   **:N-4** (Error indicates arguments out of range)

Assign   **AL X=90 Y=90**

Reply   **:N-5** (Error indicates operation failed, try entering one argument at a time)

Query   **AL X? Y? Z?**

Reply   **:A X=80 Y=50 Z=1**

Command: **AFMOVE**

Format:	**AFMOVE** [**X=**#] where **X=0** or **X=1**
Shortcut:	**AM**
Function:	A mode command that influences subsequent commanded moves. If **X=1**, then upon completion of a commanded XY move (**MOVE** and **MOVREL**), for example, **MOVE X=123 Y=456**, a multi-axis controller will then automatically initiate an auto-focus.
Response	**:A** or Error Reply.
<u>Examples:</u>	**AM X=1** **:A<CR><LF>**
Query	**AM X?**
Reply	**:A X=1**

Command: **AFOCUS**

Format:	**AFOCUS X=** [% of *speed*] **Y=** [*travel distance* in mm] **Z=** [*Hill Detect enable*] **F=** [*Hill Offset*]
Shortcut:	**AF**
Function:	The **AFOCUS** (or **AF**) command will invoke an auto-focus routine using the *speed* and *travel* range specified by the previously set **X** and **Y** parameter settings. This routine can also be activated by pressing "@" button on most controllers. Entering **AF** without arguments will initiate the auto-focus routine itself, whereas issuing an **AF** with arguments will only set the parameters. An auto-focus scan can be canceled with **HALT** command or by issuing the "****" shortcut. When an **AF** command is issued, the controller only replies after the operation is complete. It returns a **:A[###]** if the operation was successful, or **N-5** if there was an error.

X= *Speed*. Range is **0** to **100** denoting the percentage of the focus drive's maximum possible speed to travel during an auto-focus scan. This speed is also used by the **AFCALIB** (or **AFC**) command.

Y= Total scan range in millimeters. The focus controller moves down one-half this *travel distance*, and then scans up the full *travel distance*. This range is also used by **AFCALIB** (or **AFC**) command.

Z= Search type; either **0** or **1**. A value of **0** enables *Normal* mode, while a **1** enables *Hill Detect* mode. (Z values 2 and 3 are reserved for future use.)

F= *Hill Offset*. Range is **0** to **100** denoting a percentage of a hill. If the Search Type is *Hill Detect*, then this setting determines when the scan will end. Once a

hill peak is detected, the scan will terminate when past the peak by the *Hill Offset* percentage value.

Response	**:A** or Error Reply (see below).

Examples:
```
AF
:A<CR><LF>
```

Assign	**AF X=5 Y=0.1 Z=0**
Reply	**:A**
Assign	**AF X=10 Y=0.3 Z=1 F=10**
Reply	**:A**
Assign	**AF X=200 Z=2**
Reply	**:N-4** (Error indicates arguments out of range)
Query	**AF X?**
Reply	**:X=10 A**
Command	**AF**
Reply	Returns **:A [*quality#*]** after operation is complete, an **:N-5** if the operation failed, or an **:N-50** if the focus drive's clutch is disengaged (if applicable).
	When all of the arguments are omitted, the **A** is transmitted after the focusing scan has completed. The number in brackets is the difference between *focus value* when in-focus compared to when out-of-focus. It indicates the quality of focus obtained.

Caution: *To protect the optical assembly and sample, ensure that the sample is at least* 200 μm *away from the optics and that the current position is zeroed, that is, the LCD display shows* Z: 0.00000> 0.00000 *before sending the* **AF** *command to the controller* (where Z is the focus axis).

Some standard MS-2000 commands may also be useful for auto-focus scripts. For example, the **RDADC Z** command can be used to directly read the *focus value*. Checking the *focus value* to verify that it is in an acceptable range could ensure that successful focus has occurred.

:N Error Codes

Code	Description
-1	Unknown command
-2	Unrecognized Axis Parameter (valid axes are dependent on the controller)
-3	Missing parameters
-4	Parameter Out of Range
-5	Command Failed, operation not performed.
-6	Undefined Error

Code	Description
−50	Clutch is Disengaged or axis disabled

Auto-Focus Low Level Command (version 8.8+)

See the Low Level Format for a complete listing of all MS-2000 serial commands and details of the RS-232 interface: http://www.ASIimaging.com/pdfs/LowLevelFormat.pdf

Low level command set is ideal Ms2000 interface for scripts/non humans. Since the commands are so rigid and streamlined, parsing on both sides should be a lot easier. Most frequently used autofocus commands are implemented in the low level command set. All values specified through this section of the manual are hexadecimal.

Command: Perform Autofocus

Byte#	Function	Possible Values
1	Axis Identifier	`0x18/0x19/0x1A/ 0x1B`
2	Command	`0x5A`
3	Termination	`0x3A`

1st Byte: is the Axis Identifier, this can be any of the valid axis identifier (0x18/0x19/0x1A/ 0x1B). The MS2000 already knows the Autofocus axis. We only have it, to keep it consistent with rest of the low level command set.
2nd Byte: is the command. Its 0x5A, same as the Autofocus scan edit command, when this is followed by the termination byte, Ms2000 knows to perform autofocus command.
3rd Byte: is the termination character ":" in ASCII or 0x3A in hex. If not received, MS2000 ignore the command.

Response: `0x01` or `0x02` (At the end of the autofocus scan, either 0x01 or 0x02 are returned.

0x01 means scan complete and successful. 0x02 means scan complete but failed to find best

focus spot)

Example   `0x18 0x5A 0x3A`

Reply   `0x01`

Command: Read Autofocus Settings

Byte#	Function	Possible Values
1	Axis Identifier	`0x18/0x19/0x1A/ 0x1B`
2	Command	`0x5B`

3	Termination	`0x3A`

1st Byte: is the Axis Identifier, this can be any of the valid axis identifier (0x18/0x19/0x1A/ 0x1B). The MS2000 already knows the Autofocus axis. We only have it, to keep it consistent with rest of the low level command set.

2nd Byte: is the command. Its 0x5B. Always returns 8 bytes corresponding to various autofocus settings.

3rd Byte: is the termination character ":" in ASCII or 0x3A in hex. If not received, MS2000 ignore the command.

Response:

Byte#	Function	Example 1	Example 2
1	LSB of autofocus scan range in 10th of a micron	`0xD0`	`0xE8`
2	MSB of autofocus scan range in 10th of a micron	`0x07` (0x07DO is 2000 in decimal..so 0.2mm)	`0x03` (0x03E8 is 1000 in decimal..so 0.1mm)
3	Autofocus Scan speed percent	`0x0A` (scan speed is 10%)	`0x05` (scan speed is 5%)
4	Current Autofocus mode	`0x00` (normal or split scan mode)	`0x01` (scan mode is Hill Detect)
5	Hill Offset percent	`0x46` (Is 70% hill offset)	`0x3C` (Hill Offset is 60%)
6	AFMOVE enable (when enable performs an autofocus automatically after each move)	`0x00`	`0x01`
7	LSB of Contrast Value	`0x0A`	`0xC8`
8	MSB of Contrast Value	`0x00` (Contrast of 10)	`0x00` (Contrast of 200)

Example   0x18 0x5B 0x3A

Reply   0xD0 0x07 0x0A 0x00 0x46 0x00 0x0A 0x00

Command: Edit Autofocus Settings

This command lets you edit the autofocus scan range, hill offset percent, autofocus mode and autofocus scan speed.

1ˢᵗ Byte: is the Axis Identifier, this can be any of the valid axis identifier (0x18/0x19/0x1A/ 0x1B). The MS2000 already knows the Autofocus axis. We only have it, to keep it consistent with rest of the low level command set.

2ⁿᵈ Byte: is the command. Its 0x5A, same as the Autofocus scan command, when this is followed by other bytes and not the termination byte, Ms2000 know that it's the edit version of the command

3ʳᵈ Byte: Number of bytes following, notifies the controller of the number of bytes following this byte.

4ᵗʰ Byte: When set to 0x01, only edits the settings, when set with 0x02 edits the settings and performs an autofocus scan.

5ᵗʰ and 6ᵗʰ Byte: Are the Least Significant byte and Most Significant Byte of the autofocus scan range entered in units of 10ᵗʰ of a micron. Maximum possible value is 0xFFFF or 65535(in decimal) or 6.5535mm

7ᵗʰ Byte: is autofocus scan speed percent. Only accepts values between 1 to 100 (0x64 in hex).

8ᵗʰ Byte: is Autofocus scanning mode. When set to 0x00 performs the normal/split autofocus scan. When set to 0x01 perform the scan in Hill Detect mode

9ᵗʰ Byte: is the Hill Offset percent

10ᵗʰ Byte: AFMOVE enable. When set to 0x01 performs an autofocus scan after every command move. Can only be either 0x00 or 0x01.

11ᵗʰ and 12ᵗʰ Byte: LSB and MSB of the Contrast Value. If the controller finds the difference between the maximum and minimum *focus value* to be less than the *contrast* value, it declares the run a failure and returns to the starting position. Maximum value allowed is 0x07D0 (ie 2000 in decimal)

13ᵗʰ Byte: is the termination character ":" in ASCII or 0x3A in hex. If not received, MS2000 ignores the command.

Response: 0x01 or 0x02 when 4ᵗʰ byte is 0x02 or else no acknowledgement is give

Byte#	Function	Example 1	Example 2	Example 3
1	Axis Identifier	0x18	0x18	0x18
2	Command	0x5A	0x5A	0x5A
3	# of bytes following	0x03	0x04	0x09
4	Perform an Autofocus scan after edit.	0x01	0x02	0x02
5	LSB of scan	0xE8	0xD0	0xE8

	range			
6	MSB of scan range	`0x03`	`0x07`	`0x03`
7	Scan speed percent	–	`0x8C`	`0x0A`
8	Autofocus Mode	–	–	`0x00`
9	Hill Detect Offset percent	–	–	`0x3C`
10	AFMOVE enable	–	–	`0x01`
11	LSB of Contrast Value	–	–	`0x0A`
12	MSB of Contrast Value	–	–	`0x00`
13	Termination	`0x3A`	`0x3A`	`0x3A`

Command string		`0x18`
		`0x5A`
		`0x03`
		`0x01`
		`0xE8`
		`0x03`
		`0x3A`
			`0x18`
			`0x5A`
			`0x04`
			`0x02`
			`0xD0`
			`0x07`
			`0x8C`
			`0x3A`
				`0x18`
				`0x5A`
				`0x09`
				`0x02`
				`0xE8`
				`0x03`
				`0x0A`
				`0x00`
				`0x3C`
				`0x01`
				`0x0A`
				`0x00`
				`0x3A`

Result		Only edits the autofocus scan range to 0.1mm and **<u>does not</u>** perform a autofocus scan in the end.	Sets the autofocus scan range to 0.2mm, ignores the edit of scan speed as the parameter is out of range and performs an autofocus scan.	Sets scan range to 0.1mm; Sets to Normal Mode; Sets scan speed to 10%; Sets Hill Detect offset to 60%. Sets Contrast Value to 10

If you just wanted to edit the scan range, then you can only update the 2 scan range bytes. But if you want to just edit the Hill Offset percent and leave all other settings unchanged, you still have to enter proper values for the bytes before it.

Example	`0x18 0x5A 0x03 0x01 0xE8 0x03 0x3A`

Reply	none
Example	0x18 0x5A 0x04 0x02 0xD0 0x07 0x8C 0x3A
Reply	0x01

AUTO-FOCUS CONTROLLER'S VIDEO PROCESSING SEQUENCE

VID IN (Video Signal in)

Set with **AL X Y**

VIDEO SAMPLER

VID MON (Video to Monitor)

NOISE FILTER

DIG POTENTIOMETER
(Video Throttle)

Set with **AFADJ Y**

AMPLIFIER

Set with **AFADJ X**

ZERO ADJUST POT

Spatial Frequency to Focus
value Converter

Set with **AFADJ Z**

ANALOG TO DIGITAL
CONVERTER