

# Command:STATUS (/)

MS2000 or RM2000 syntax

<b>Shortcut</b>	/
<b>Format</b>	STATUS

Tiger syntax

<b>Shortcut</b>	/
<b>Format</b>	STATUS
<b>Type</b>	Broadcast Command

Inquires regarding the motor status of all axes. Queries the controller whether or not any of the motors are still busy moving following a serial command.

## Reply

**N** - Not Busy: there are no motors running from a serial command

**B** - Busy: there is at least one motor running from a serial command



**Note:** Using the **/ (forward slash)** shortcut is the preferred method for rapid polling of the controller for a busy state. The shortcut is handled more quickly in the command parser.

## Example

```
MOVE X=12345
:A
STATUS
B
/
N
```

In this example, the command MOVE started the X-axis moving towards the position 1.2345 millimeters from the origin. The first STATUS command returned a B showing that the motor is still busy moving towards the target. The second time, the STATUS command returned a N signifying that the MOVE command is finished and there is no longer any motor movement. The second command (/) is processed faster.

[commands](#), [tiger](#), [ms2000](#)

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Last update: **2025/11/12 19:58**