

# Command:SETLOW (SL)

MS2000 or RM2000 syntax

<b>Shortcut</b>	SL
<b>Format</b>	SETLOW [axis]=[position in mm]...
<b>Units</b>	Millimeters
<b>Remembered</b>	Automatically

Tiger syntax

<b>Shortcut</b>	SL
<b>Format</b>	SETLOW [axis]=[position in mm]...
<b>Units</b>	Millimeters
<b>Type</b>	Axis-Specific
<b>Remembered</b>	Automatically

This command sets/displays the lower firmware limit for an axis. The limit is considered a fixed hardware locations and are adjusted properly when the controller's coordinate system is altered with the HERE or ZERO commands. The limit positions are automatically remembered and recalled through a power cycle and do not need to be saved using the [SAVESET command](#).

SL [axis]+ will set the lower limit to be the current position. Restore the default limit by executing SL [axis]-. The +/- operand syntax is supported as of Tiger firmware v2.8 and MS-2000 firmware as of roughly 2013.

The corresponding command for the lower firmware limit switch is the [SETLOW](#) command.

## Reply

If there are no errors, a positive reply of :A followed by the startup sequence. For the Z axis only, input values equal to or greater than the current SETUP parameter value are acknowledged by :A but ignored.

## Example

```
SL X=-50 Y=-50 Z?  
:A Z=-110.000
```

In the above example, the lower limit for the X and Y axes have been set to 50 millimeters from the origin in the negative direction. Note that the Z? resulted in the controller returning the current position of the Z lower firmware limit switch.

**Note 1:** If this value is equal to or greater than the value for SETUP, then the controller will operate incorrectly. See also Note 2.

**Note 2:** When the direction of an axis is negative (see [CCA Z=###](#)), upper limit settings must be negative values, and lower limit settings must be positive values.

**Note 3:** For clocked devices (e.g. filter sliders, turrets) the lower limit is always 1.

[commands](#), [tiger](#), [ms2000](#)

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