

Command:KA

Tiger Syntax

Shortcut	KA
Format	KA [axis]=n...
Units	unitless integer
Type	Axis Specific
Remembered	Using [Addr#]SS Z

MS2000 and RM2000 Syntax

Shortcut	KA
Format	KA [axis]=n...
Units	unitless integer
Remembered	Using SS Z

Adjusts acceleration gain parameter in the servo loop where n is a signed integer. The default value is 0. **MOST USERS DO NOT NEED TO USE THIS FUNCTION!**

Note: Before Tiger v3.20 and Whizkid 9.21, the KA and KADC commands adjusted the overall servo gain. KADC was primarily used for CRISP. The KA command sets the servo acceleration gain feed forward constant. The [LR T](#) command replaced KADC for CRISP.

```
KA Z?  
:A Z=0
```

[commands](#), [tiger](#), [ms2000](#)

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